



# Status and Progress of ARGO

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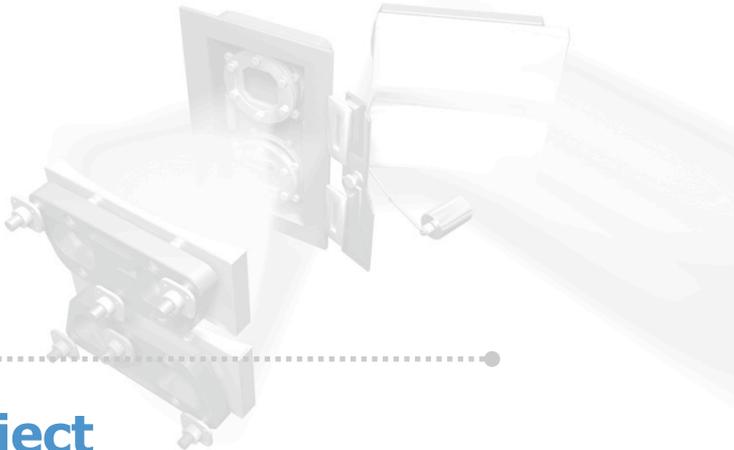
**Young Su Son**

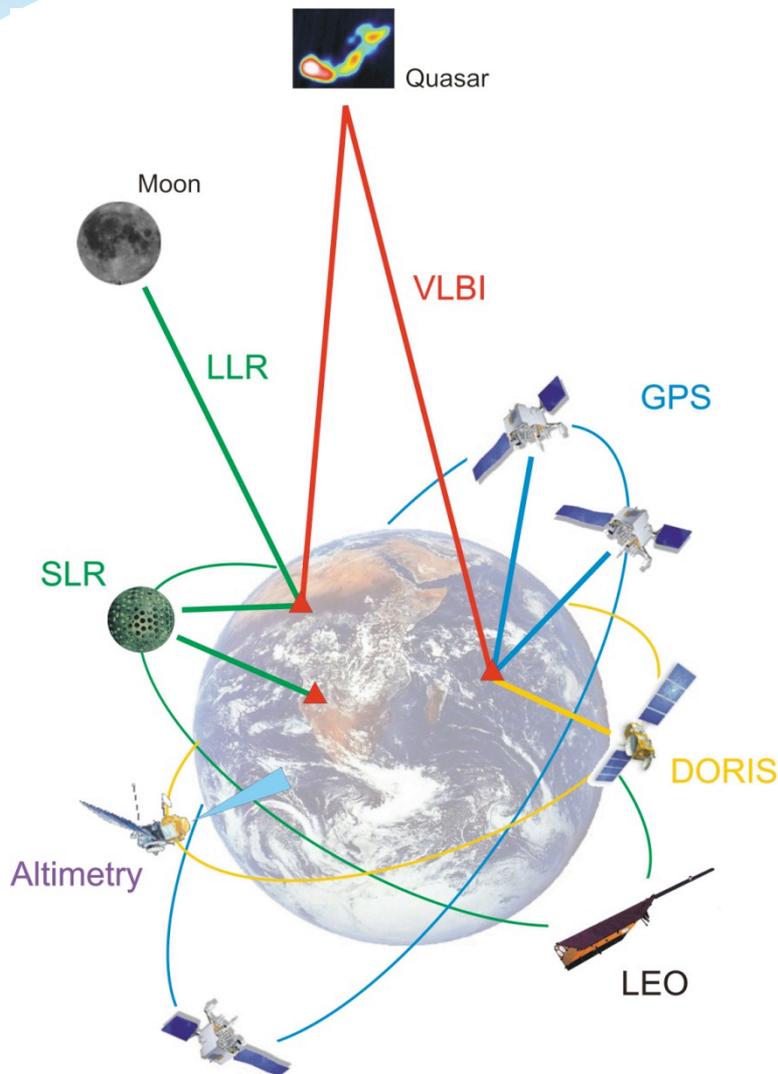
*Korea Institute of Machinery and Materials*

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*Kongju National University*



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  - 3 **Requirements of ARGO System**
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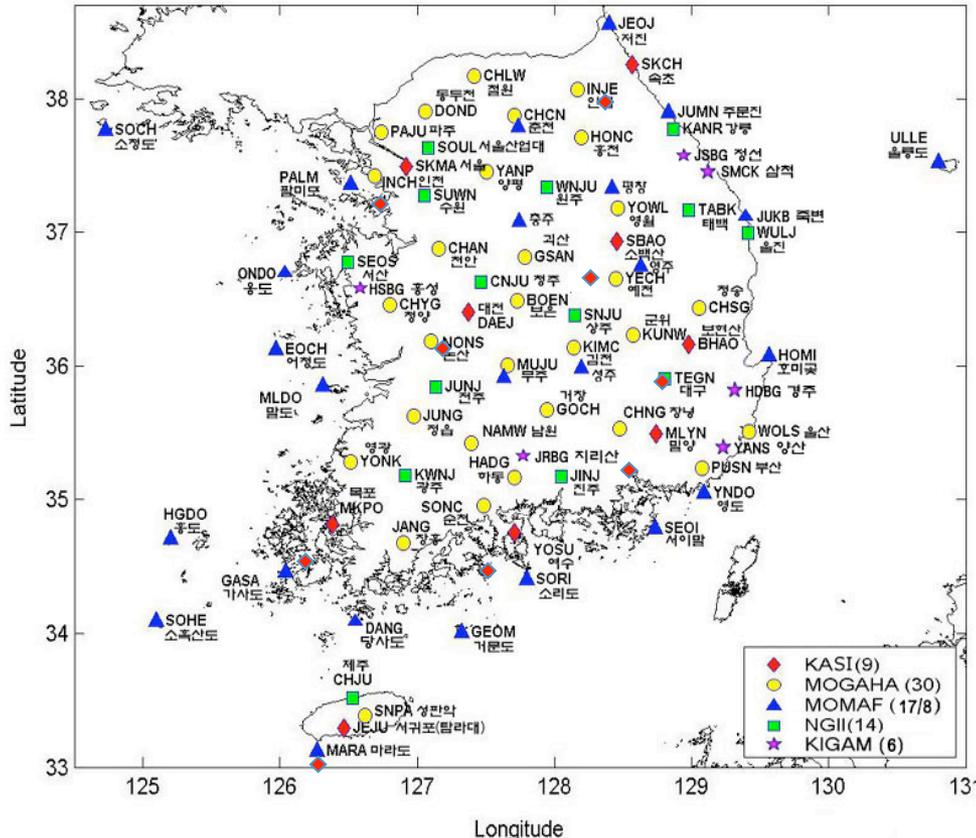


The objective of this presentation is to show the current status and forthcoming steps of ARGO project; Korea an new SLR systems.

Space Geodesy in KASI was started from early 90's and now...

- ✓ 9 permanent GPS sites
- ✓ IGS site (DAEJ)
- ✓ IGS Global Data Center
- ✓ 3 VLBI & Correlation Center
- ✓ Space Mission (KOMPSAT-5)
- ✓ Geodynamics, GNSS meteorology, Gravity, and other applications with very passionate staffs.

## Korean GPS Networks



한국천문연구원 Korea Astronomy and Space Science Institute (KASI)

행정자치부 Ministry of Government Administration and Home Affairs (MOGAHA)

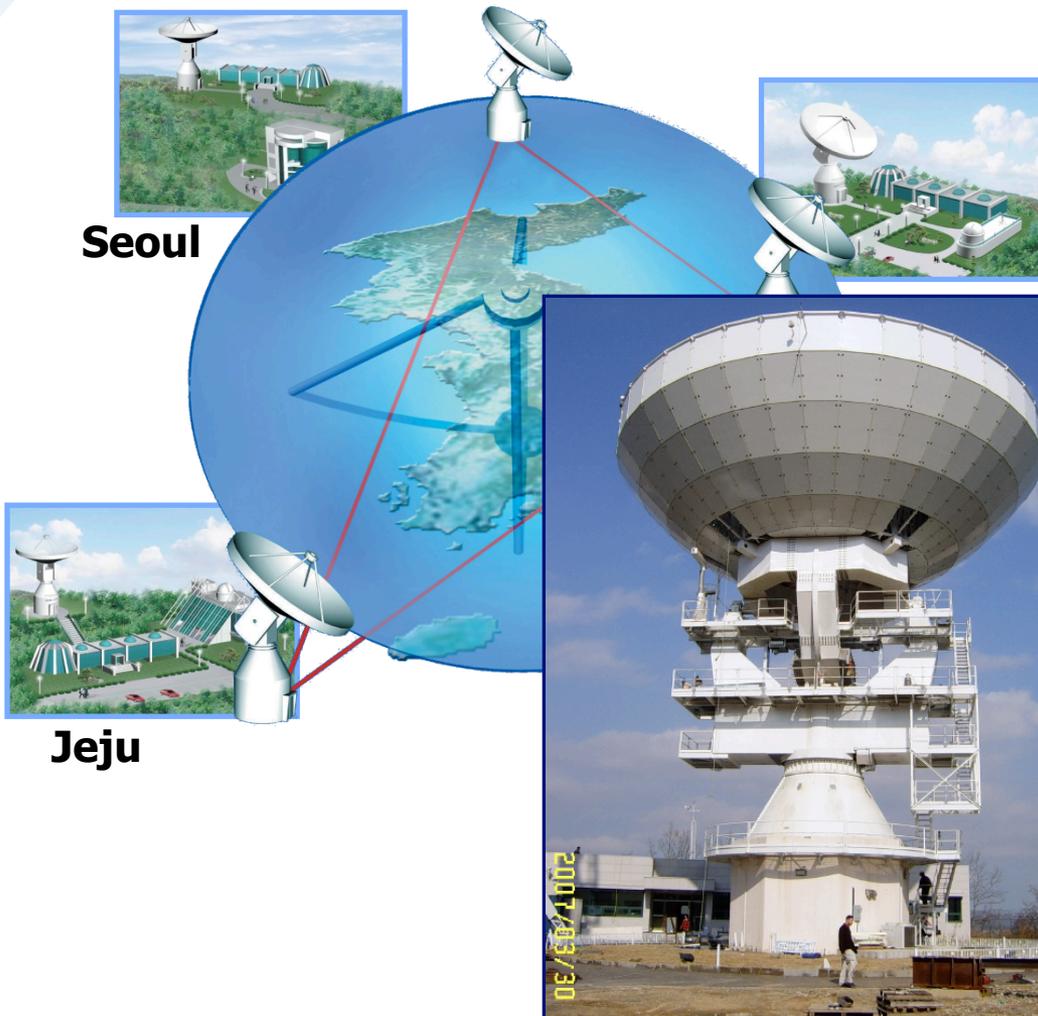
해양수산부 Ministry of Maritime Affairs and Fisheries (MOMAF)

국토지리정보원 National Geographic Information Institute (NGII)

한국지질자원연구원 Korea Institute of Geoscience and Mineral Resources (KIGAM)

- ❑ 85 GPS Reference Stations including 2 IGS sites operated by 5 Agencies or Institutes
- ❑ Well-distributed, nationwide GPS network with 20~50 Km inter-spacing
- ❑ National Reference of Geodetic Coordinate, Mapping, Survey, Cartography, Navigation, ITS, LBS and Space Geodesy
- ❑ Modernization plan for next generation GNSS services in near future

## Korean VLBI Networks

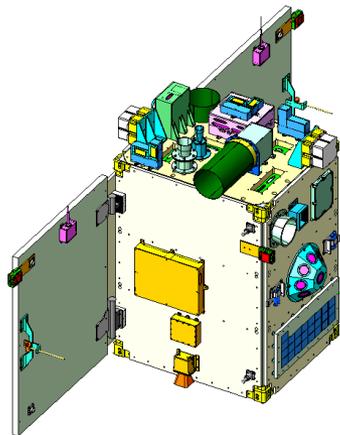


- ❑ Three 21m Antennas
- ❑ 2001-2008 by KASI
- ❑ Astronomy/Geodesy

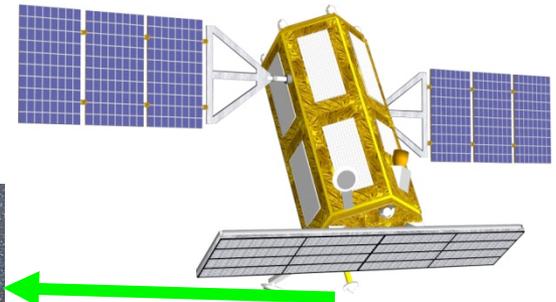
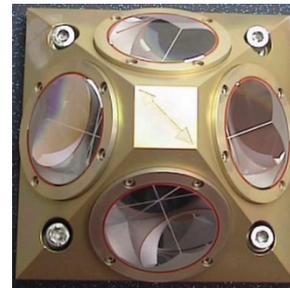
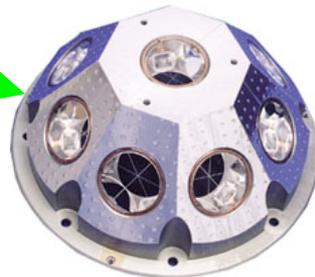
Main Spec.	
Diameter	21m
Mounting	AZ/EL type
Aperture Efficiency	60%(@100GHz)
Operating Range	AZ :± 270°, EL: 0~90°
Operating Speed	1"/sec ~ 3°/sec
Max. Acceleration	3°/sec <sup>2</sup>
Pointing Accuracy	4" @ wind 10m/sec
Surface Accuracy	65 μm(Manufacturing)
Total Accuracy	150 μm (@wind 10m/s)
Frequency	2/8GHz, 22GHz, 43GHz 86GHz, 129GHz

## Korean SLR System

- ❑ Feasibility Study on Korean SLR system in 2004/2005
- ❑ Planning Study on the R&D Project for SLR in 2005/2006
- ❑ **Development of Korean SLR Systems from 2008**
  - **40 Cm Mobile (ARGO-M) in 2011 and 1 M Fixed (ARGO-F) in 2013**
- ❑ STSAT-2 in 2009 and KOMPSAT-5 in 2010



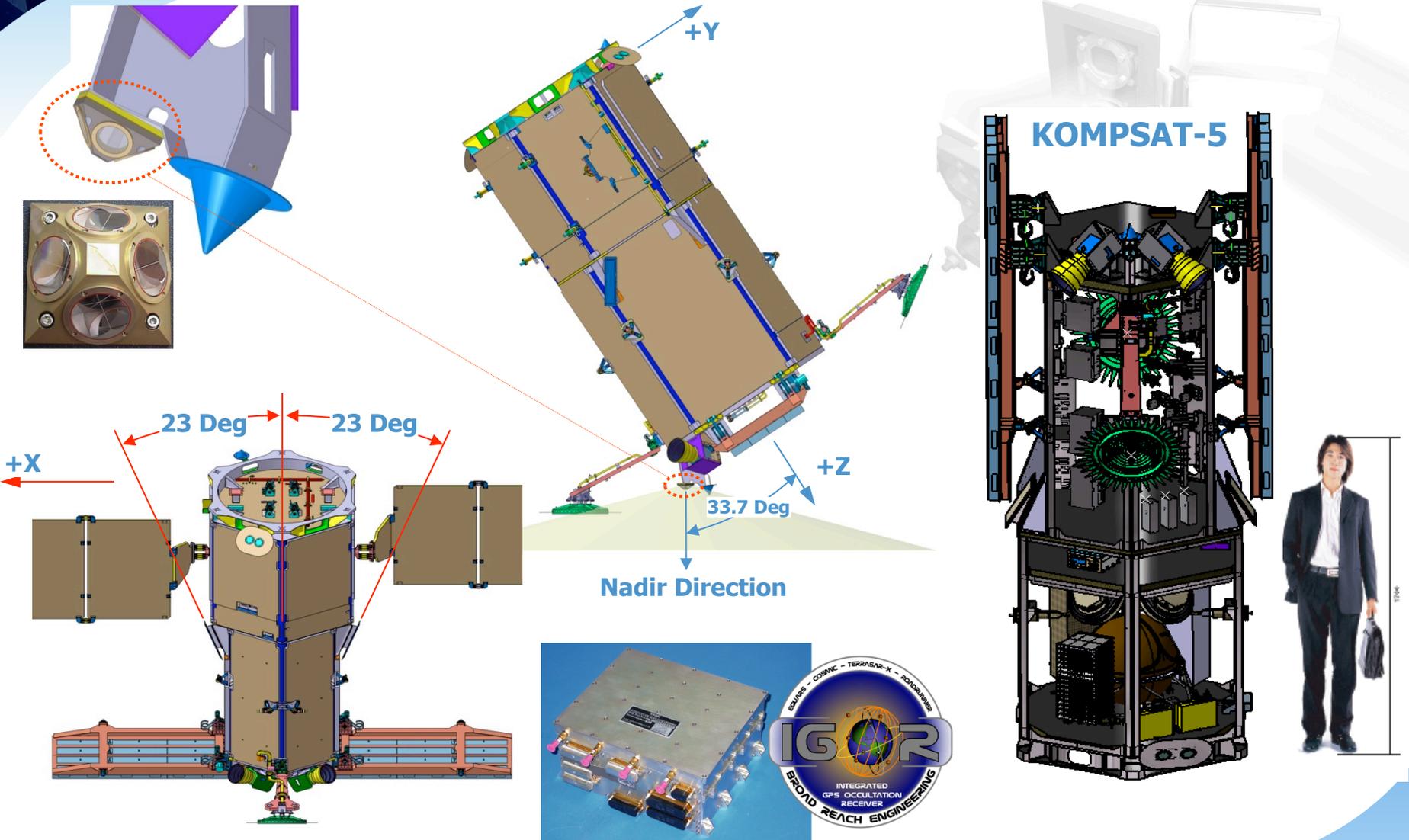
(STSAT-2)



(KOMPSAT-5)

Laser Retro-Reflector Array

# Backgrounds – KOMPSAT 5



- ❑ **ARGO:** Accurate Ranging system for Geodetic Observation
  - The Name of Korean SLR program
  - It comes from the ship on which a great group of heroes boarded to find the Golden Fleece in the ancient Greek mythology
  - means also a group of specialists to carry out a great mission
- ❑ **Development Phase: 2008 – 2013 (6 years)**
- ❑ **Final Goal**
  - One fixed system(1m) and one mobile system(40cm)
- ❑ **Team members & Supporters**
  - KASI, KIMM, KAERI, SatRec & Kongju Univ.
  - Advisory Committees, ILRS, ... **All of You!!**

## ❑ Tracking Coverage

- Possible to track satellites in the [altitude of 25,000km](#)
- STSAT-2, KOMPSAT-5, GPS, Galileo Satellites

## ❑ Ranging Accuracy

- [Lageos : 10mm\(SS\), 2-3mm\(NP\)](#)
- GPS and Galileo : 20mm(SS), 3-5mm(NP)
- Ground Target : 3mm(SS), 1mm(NP)
- Epoch for NP data within  $0.12\mu\text{s}$  of GPS time

## ❑ Automatic Operation

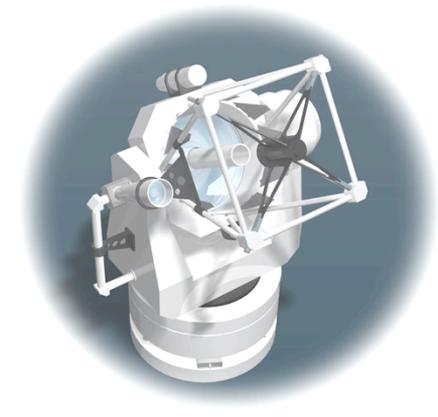
- All system can be [controlled from the remote site](#) for the SLR systems
- [Automatic](#) observation according to the schedule and aircraft detection using radar
- Automated calibration by star camera and ground target
- Automated scheduling, planning and orbit prediction capability
- Automated diagnostic warning to network monitor

## ❑ Etc

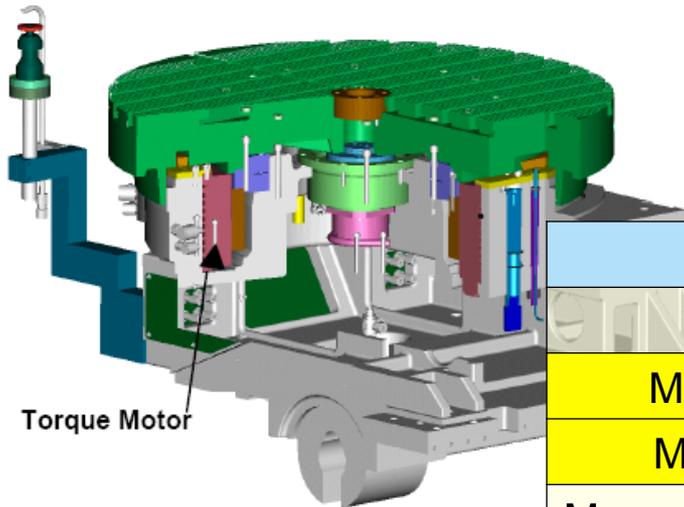
- [Daylight tracking](#)
- [Optical tracking](#) for the spacecraft and space launch vehicle (ARGO-F)

## Optics system

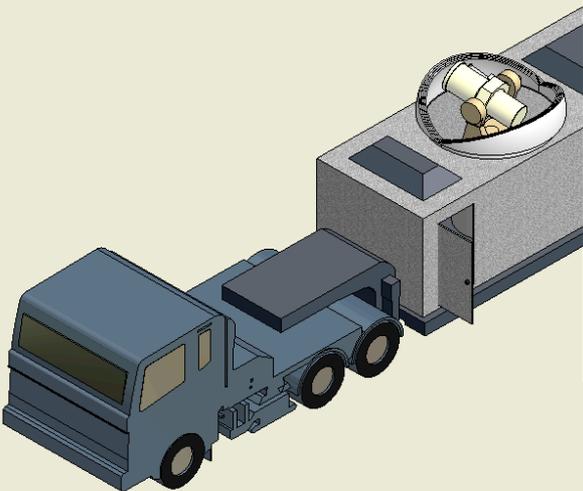
Classification		ARGO-M	ARGO-F
Rx Telescope	Type	Cassegrain	Richey-Cretien
	Aperture(cm)	40	100
Tx Telescope	Type	Refractor	Richey-Cretien
	Aperture(cm)	10	100
Generals	M1 F Ratio	1.5	
	FOV	10 arc minutes	50 arc seconds
	Tube Length	975 mm	1425 mm
Materials		Zerodur/CFRP	
Tx.Rx path		Separate	Perforate mirror
Daylight filter		Oven controlled spectral filter	Fabry-Perot
Daylight Filter Bandwidth( nm)		0.3	1



## Tracking Mount



Classification	ARGO-M	ARGO-F
Mount Type	EL over AZ	
Max slew rate Az (deg/s)	20	
Max slew rate El (deg/s)	10	
Max used tracking rate Az (deg/s)	$\geq 5$	TBD
Max used tracking rate El (deg/s)	$\geq 2$	TBD
Pointing accuracy (arc sec)	TBD	$\leq 5$
Angle encoder accuracy (")	$< 0.1$	
Min. tracking elevation (deg)	15	15
Motors	PMSM Torque Motors	
Motor control	Servo control	
Drive type	Direct drive	



## Laser system

Classification	ARGO-M	ARGO-F
Laser type	Nd:YAG	Nd:YAG
Primary wavelength (nm)	1064	1064
Primary max. energy (mJ)	Not used for ranging	Not used for ranging
Secondary wavelength (nm)	532	532
Secondary max. energy (mJ)	1	20
Xmit energy adjustable	No	Yes
Pulse width(FWHM) (ps)	10	<100
Max. repetition rate (Hz)	1000	20
Fullw. Beam divergence (")	5-200	7-60
Eye-safe	No	No

by Y.K.Seo 2008-09-04

## ● Optoelectronics system

Classification		ARGO-M	ARGO-F
Chain wavelength		532	532
Detector	Type	CSPAD	CSPAD
	FoV (°)	40-60	12
Signal Processing	Type	Time walk compensated	Time walk internally
	Amplitude measurement	N/A	Yes
	Return-rate controlled	Yes	Yes
	Mode of operation	Muti photons	Single to Multi photons
Time of Flight Observation	Type	Event timer	Event timer
	Resolution (ps)	<1.5	<1.5
	Precision (ps)	<10	<10

## ● Operation and Control system

Classification		ARGO-M	ARGO-F	
Tracking Capabilities	Satellites	GPS (21,000km)	Yes	Yes
	Average values for Lageos	Single shot RMS (mm)	8	<10
		# of obs. per NP	~ 12,000	~ 100
	Range gate width (ns)		200	200-5,200
	Beam pointing accuracy(")		5	2
	Operation	Secondary Mission	Nothing	Optical tracking
Remotely controllable		Yes	Yes	
Calibration	Calibration type/location		Pre+Post / External	Pre+Post / External
	Mode of operation		Few photons	Single to multi
	Single shot RMS (mm)		<3	<3
Frequency Standard	Type		Crystal oscillator	Crystal oscillator
	Epoch accuracy (ns)		<100	<100
Preprocessing information	On-site NP generation		Yes	Yes
	Upload interval		Daily	Daily
Aircraft detection		Radar + ATC data	Radar + ATC data	

# Milestone of ARGO Development

 Univ.  
  Institute  
  International cooperation

ARGO	1st Stage			2nd Stage		
	2008	2009	2010	2011	2012	2013
	▲ SRR ▲ SDR ▲ PDR ▲ CDR			▲ Complete (10.10)▶		
ARGO-M (Mobile)	Spec. decision    SDR/PDR/CDR (Optics, Mount, Dome, etc)   SDR/PDR/CDR (Operation, Photon-electronics)	Development & Manufacture System Integration Outsourcing (Laser, Additional systems)		   Test Operation & Solving problems	SRR(08.07) SDR(08.11) PDR(09.04) CDR(09.09)	
ARGO-F (Fixed)	▲ SRR (08.07)   ▲ SDR (09.03)   ▲ PDR (09.10)   ▲ CDR (10.10) Spec. decision    SDR/PDR/CDR (Optics, Mount, Laser, Photon-electronics)   SDR/PDR/CDR (Operation, Remote Control system)	Site candidate surveying Site decision & Station Design Outsourcing (Additional systems)	Development & Manufacture Station Construction Outsourcing (Additional systems)	System Integration Test Operation & Solving problems	▲ Complete (12.12)▶	
Remarks	TRDS (China) Operation		ARGO-M	ILRS Associate AC	ARGO-F	
	STSAT-2 Launch		KOMPSAT-5 Launch		Laser Tracking (STSAT-2, KOMPSAT-5)	



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## ARGO System

- ARGO, the name of forthcoming Korean SLR Systems, officially started from Jan. 1<sup>st</sup>, 2008 to build a 40 cm mobile SLR system and 1 meter fixed SLR system.
- The lightweight telescopes, a KHz laser, remote control and fully automation concept are introduced for ARGO-M & ARGO-F.
- ARGO will be the member of ILRS sites in 2012 and 2014, respectively

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## Related Missions

- Space Programs equipped with LRRR
  - ✓ STSAT-2 in 2009 & KOMPSAT-5 in 2010
- Planned fundamental Station in Korea
- Korean 2th science complex in Antarctic
- ILN Program & Lunar Exploration 2020 Project



# Thank you !!!

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